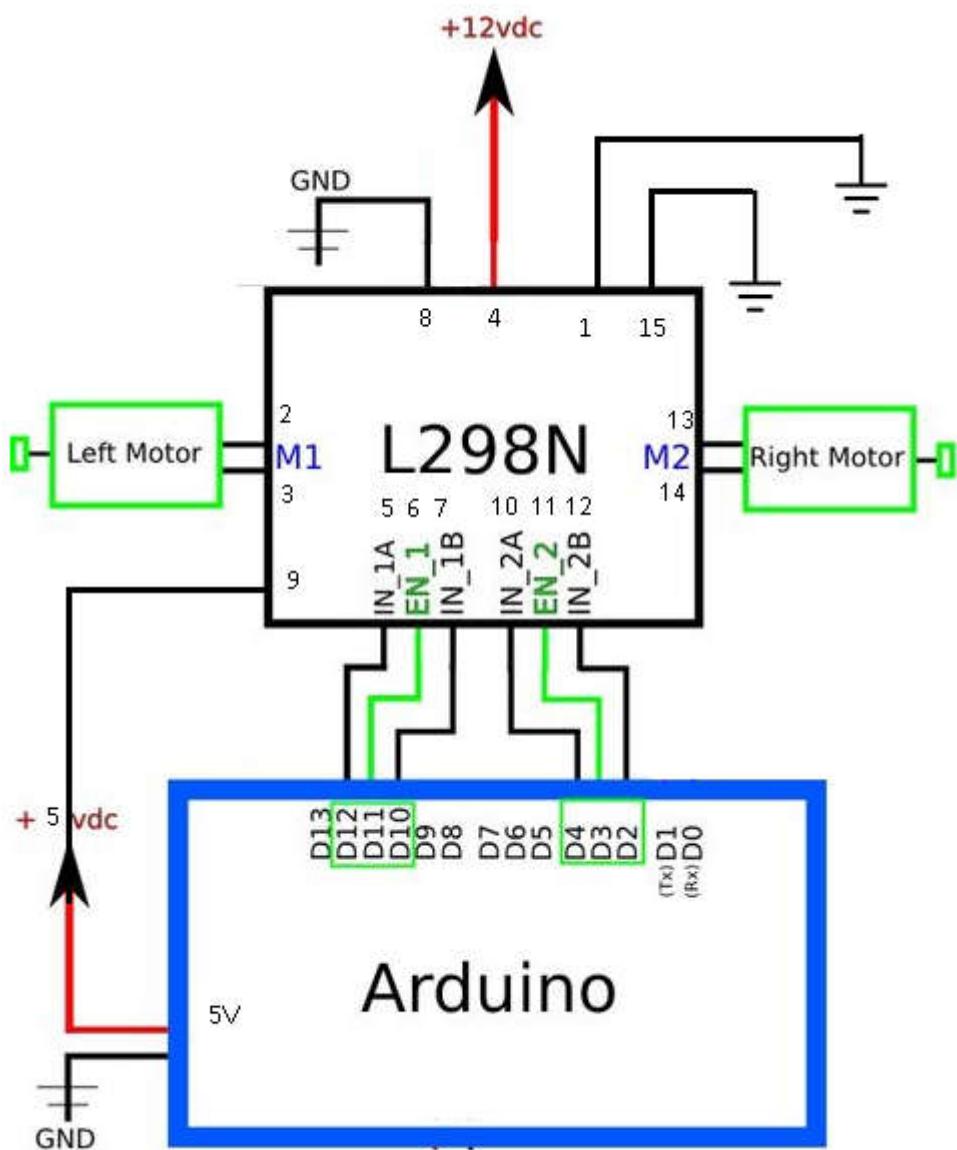


ARDUINO + L298 + DC MOTOR



```
int IN_1A = 12; int EN_1 = 11; int IN_1B = 10;
int IN_2A = 4; int EN_2 = 3; int IN_2B = 2;
int m1speed=50; //max 255

void loop() {
  digitalWrite(IN_1A, HIGH);
  digitalWrite(IN_1B, LOW);
  analogWrite(EN_1, m1speed);

  digitalWrite(IN_2A, HIGH);
  digitalWrite(IN_2B, LOW);
  analogWrite(EN_2, m1speed);
  delay(5000);
}
```